



# Progress Report to Advisory Board

## Undergraduate Education

Mel Gomez

Associate Chair for Undergraduate Education

- Freshmen Admission/ Enrollment/Graduation Data
- ABET Self-Study Updates
- UMD-EE SMD Updates
- New Course Focus: ENEE 408R

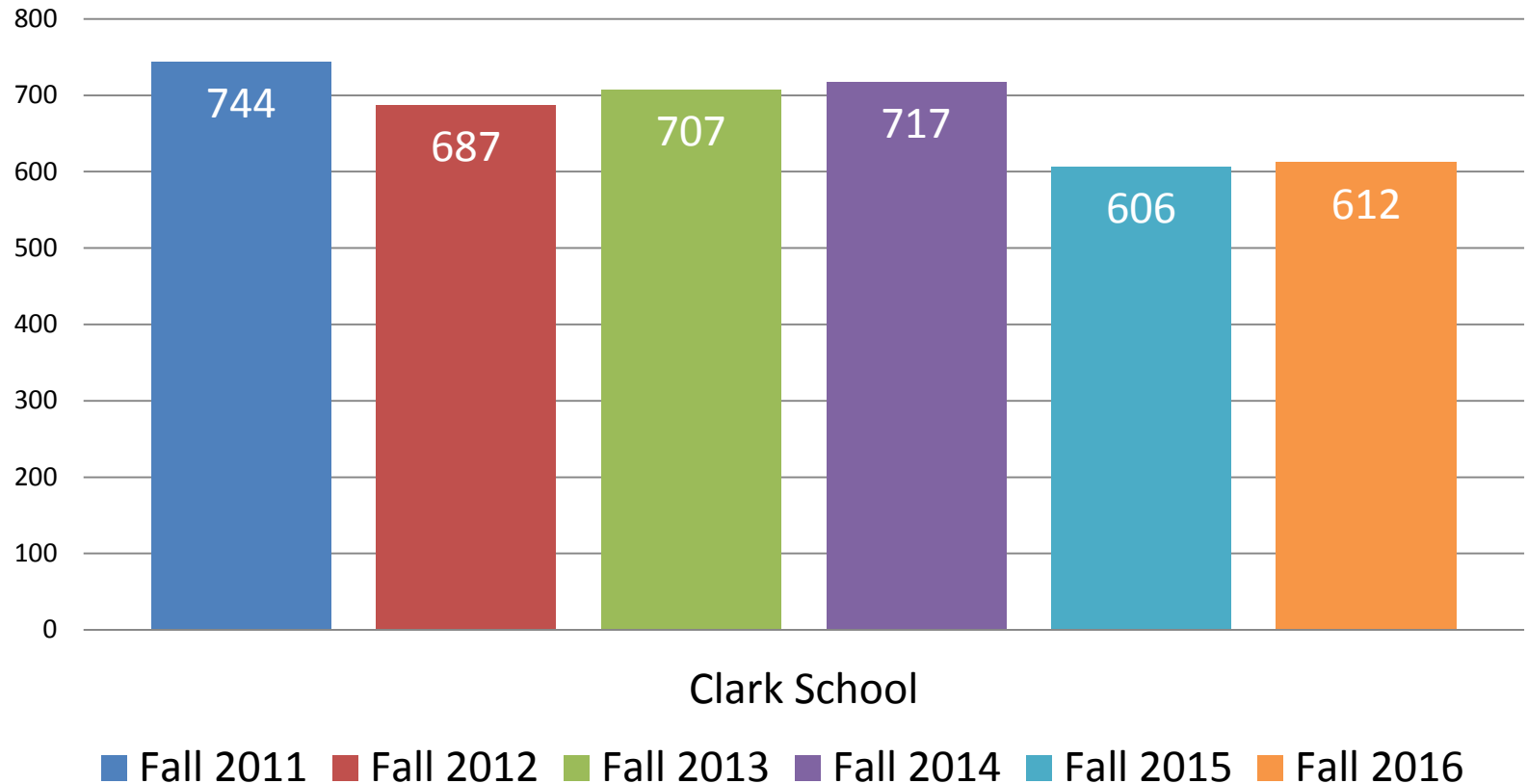


# Undergraduate Staff

- Neruh Ramirez, Director
- Kathryn Weiland, Asst. Director
- Jennifer Wivell, Adviser
- Mary Walters, Adviser
- Pamela Talbott, Program Admin Specialist

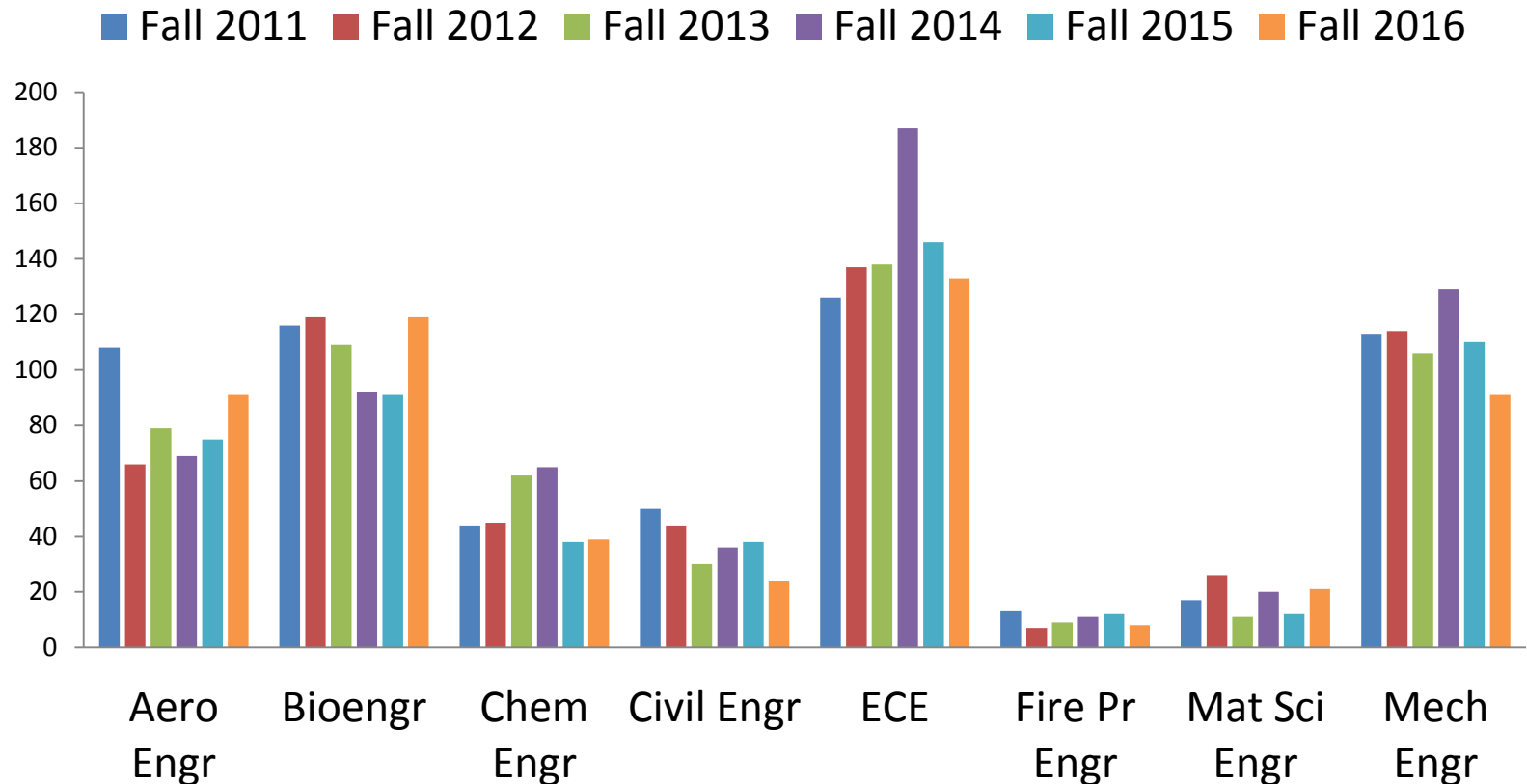
# A.J. Clark School Freshmen Enrollment

2011-2016



# ENGR Freshmen Enrollment

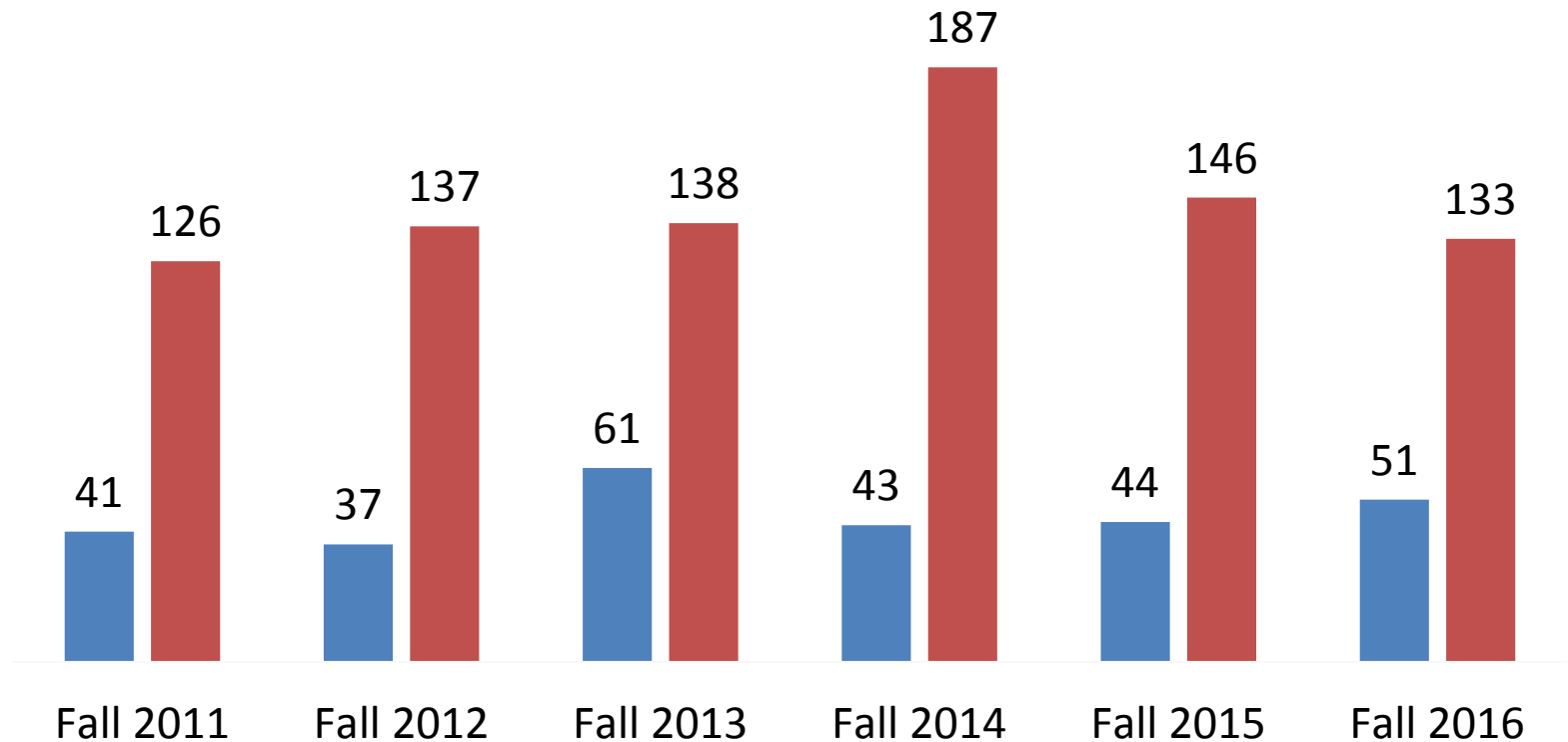
## Clark School of Engineering Fall 2011-2016



# ECE Freshmen/Transfer Enrollment

2011-2016

■ New Transfer ■ New Freshmen

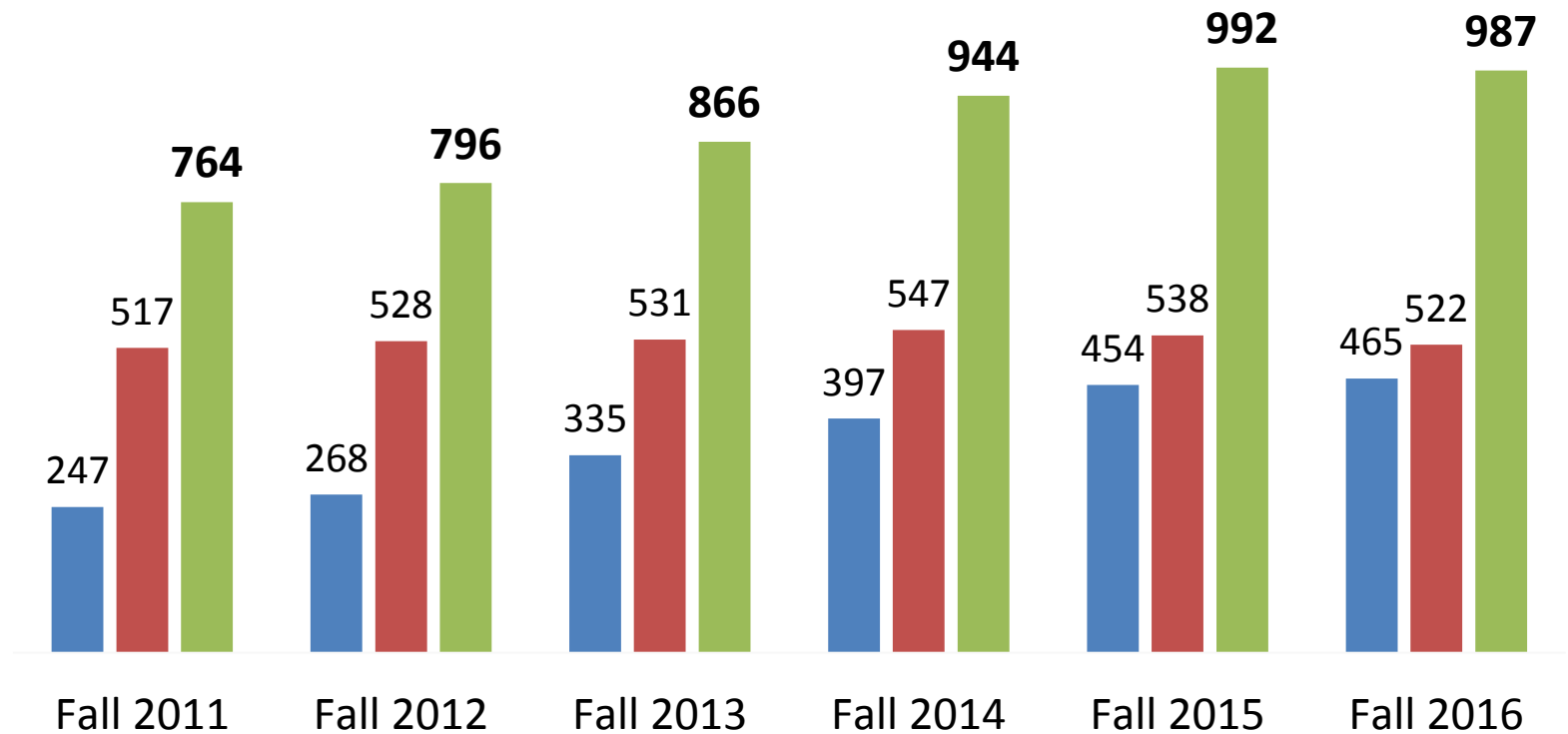


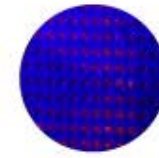
Anticipated Enrollment Fall 2017 = 188

# ECE Total Enrollment

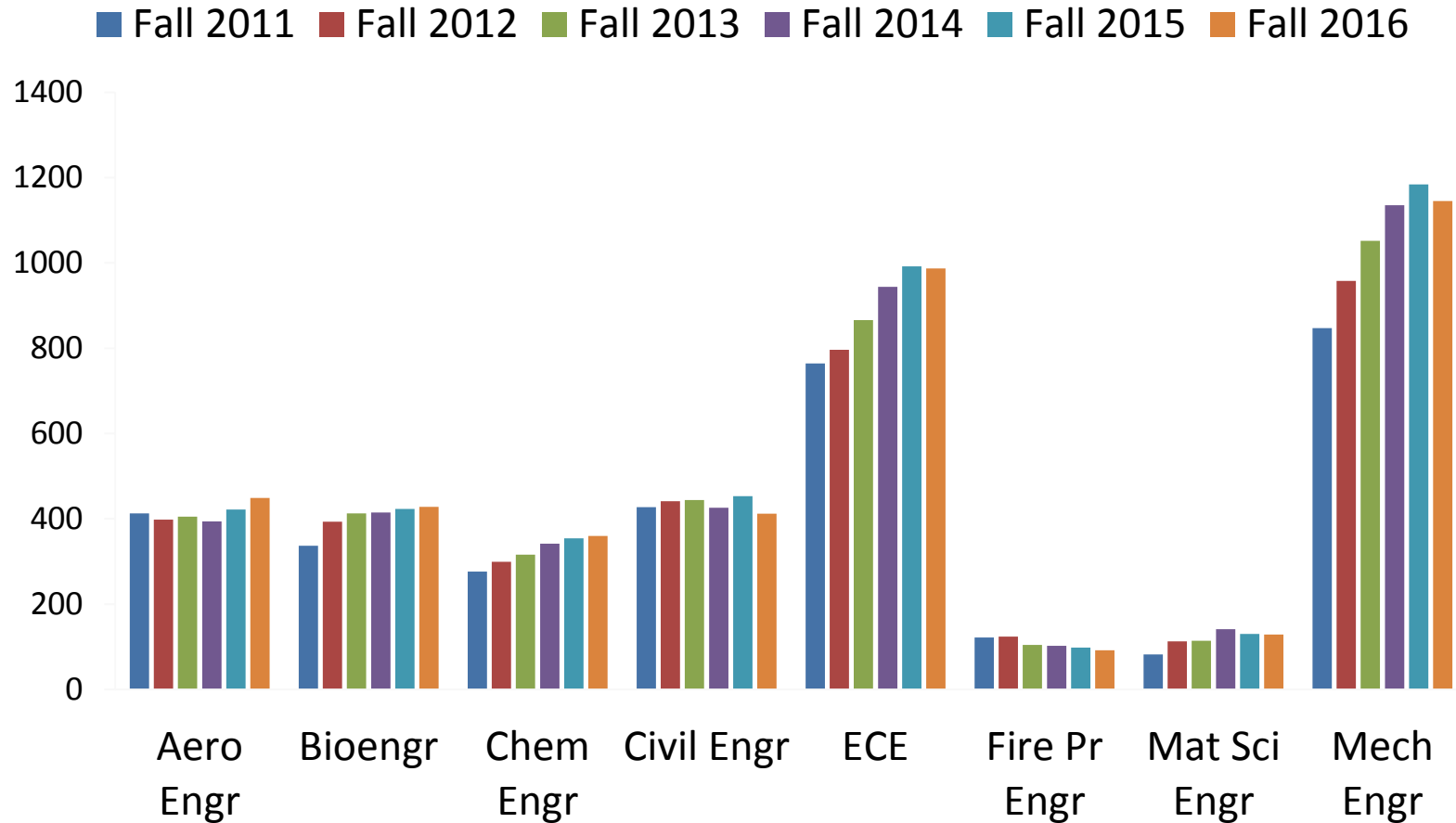
2011-2016

■ Computer Engineering ■ Electrical Engineering ■ Total ECE Enrollment

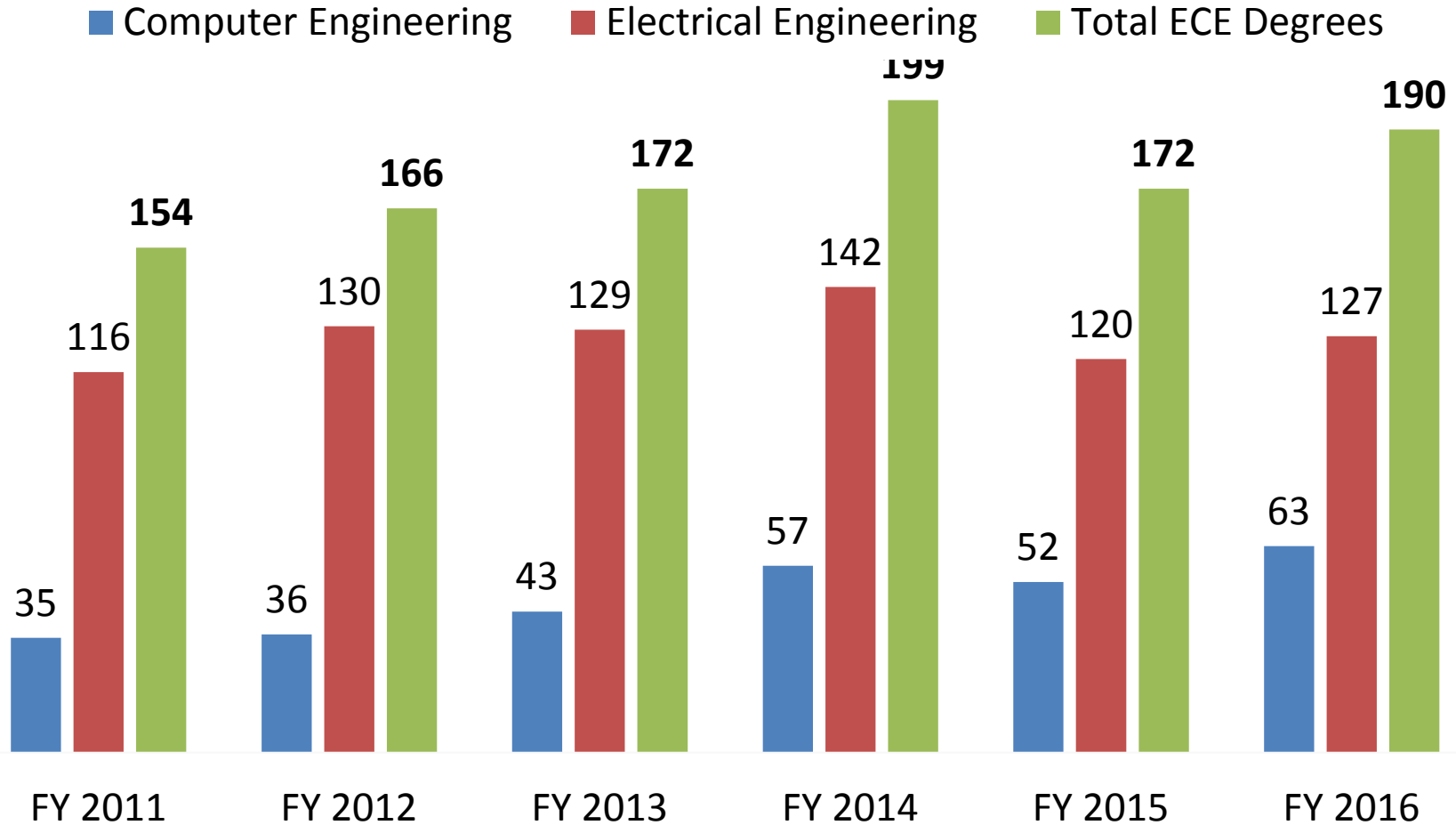




## ENGR Undergraduate Enrollment 2016



# ECE Undergraduate Degrees 2011-2016







# ABET

- Important Dates:

EE and CpE **Self-Study Reports** due on July 1, 2017

Program Evaluators visit in October, 2017




# Summary of Major Changes since last ABET Visit

- PEO Revised and Approved by Faculty
- Standardized assessment methods for Capstone Courses
- Nine (9) New Courses
  - ENEE 101 – Introduction to ECE
  - ENEE489A – Small Antennas
  - ENEE459B - Reverse Engineering and Hardware Security
  - ENEE439M - Machine Learning
  - ENEE408R – Electric Bikes
  - ENEE447 – Operating Systems
  - ENEE459E - Introduction to Cryptology
  - ENEE459V - Introduction to Embedded Systems
  - ENEE476 - Renewable Energy
- Improved Laboratory Infrastructures
  - Texas Instruments Discovery Laboratory
  - Jimmy Lin Advanced Electronic Devices Laboratory
  - Hughes Network Communications Laboratory
- Established New Computer Engineering Minor for EE and other Majors
- Established Satellite EE Program in Southern Maryland (SMD-EE)



# EE and CpE Self-Study Reports

- Background
- Criterion 1-Students
- Criterion 2-PEOs
- Criterion 3-Student Outcomes (a-k)
- Criterion 4-Continuous Improvement
- Criterion 5-Curriculum
- Criterion 6-Faculty
- Criterion 7-Facilities
- Criterion 8-Institutional Support



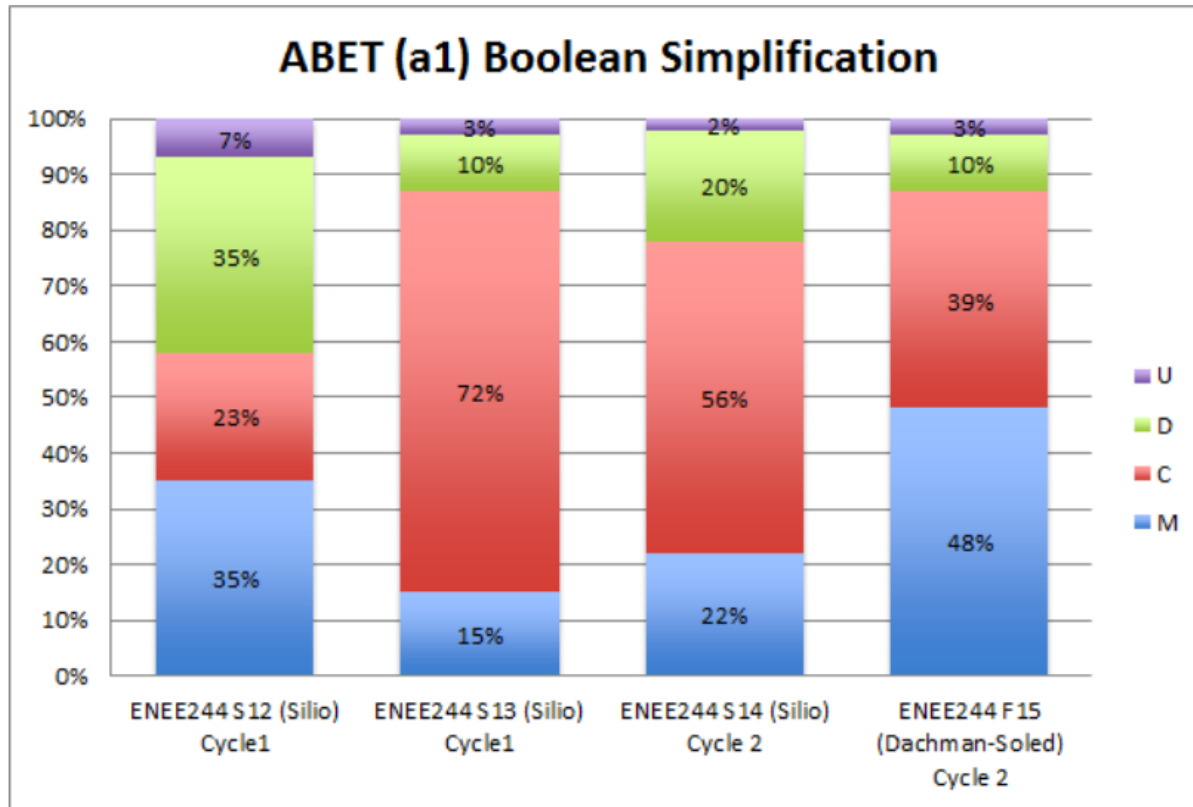
# Criterion 1. Students

- Clark School Admission Standards
- Internal and External Transfer Admission Criteria
- Student Performance Review and Academic Success
- Advising and Career Guidance
- Graduation Requirements

\*sample transcripts will be provided to program evaluators

# Criterion 4. Continuous Improvement

- Simplified Assessment Strategy



**Figure 4(a1):** ABET (a1) Assessment Summary Results for Cycle 1 and Cycle 2. (M=Mastery, C=Competent, D=Developing, UD+Underdeveloped)

## ABET Outcome

(a) an ability to apply knowledge

(b) an ability to design and communicate and interpret data

(c) an ability to design a system needs within realistic constraints political, ethical, health and safety

(d) an ability to function on a multidisciplinary team

e1. identify, formulate, and solve a transient problem

e2. identify, formulate, and solve a steady

ENEE205

ENEE205

Design Validation

Transient Analysis

Transient Analysis

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Design Validation

Transient Analysis

# Criterion 5. Curriculum

## BS EE (120 credits)

– Math & Science		29
– ENES100		3
– ENEE101		3
– Disciplinary Foundation		39
– EE Technical Electives	13	
– General Tech Electives		12
– Professional Writing		3
– Gen Ed		18

## BS CpE (122 credits)

– Math & Science		25
– ENES100		3
– ENEE101		3
– Disciplinary Foundation		48
– Technical Electives		22
– Professional Writing		3
– Gen Ed		18

# Criterion 6 – Faculty

- Professors - 45
- Associate Professors - 7
- Assistant Professors - 5
- Adjunct/Emeritus - 13

Ten (10) NSF Presidential Young Investigator (PYI) Award

One (1) ONR Young Investigator

Two (2) Presidential Early Career Award for Scientists or Engineers (PECASE)

Ten (10) NSF Research Initiation Awards

Eighteen (18) recipients of NSF CAREER Awards



Thirty-Five (35) IEEE Fellows

Two (2) ACM Fellows, Seven (7) APS Fellows, Five (5) OSA Fellows

Three (3) AAAS Fellows, One (1) IOP Fellow

Three (3) Distinguished University Professor

Nine (12) Distinguished Scholar/Teacher



# Criterion 7 – Facilities

## (13 Teaching Laboratories)

- BAE Control Systems Lab
- Computer Lab
- Hughes Communications Design Lab\*
- Electrical Machines Lab
- Jimmy Lin Advanced Electronics Design Lab\*
- Electric Circuits Lab
- Jasmine Telecommunications Lab
- Fabrication Lab (Kim)
- Microcomputer Lab
- Microelectronics Design Lab
- Photonics Lab
- TI Discovery Lab\*
- Systems Engineering and Integration Lab



# UMD SMD-EE STATUS

Start: Fall 2017, currently 10 students registered in the program

## Fall Semester

- ENEE 303 Analog and Digital Electronics @SMHEC, in person
- ENEE 322 Signals and Systems Theory @SMHEC, online
- ENEE 350 Computer Organization@SMHEC, online
- ENEE 380 Electromagnetic Theory @SMHEC, in person

## Winterterm

- ENEE 200 Ethics @UMD, online
- ENGL 393 Technical Writing @UMD, online

## Spring Semester

- ENEE 307 Electrical Circuits Design Lab @SMHEC, in person
- ENEE 313 Introduction to Device Physics @SMHEC, in person
- ENEE 324 Engineering Probability @SMHEC, online
- ENEE 381 EM Wave Propagation @SMHEC, in person
- ENEE 4XX Transform Methods @SMHEC, in person



# Courses to be offered in senior year

## **Fall Semester** (5 courses)

ENEE 425N Signal Processing @SMHEC

ENEE 4XX Advanced Laboratory @UMD

ENEE 490N Wireless Communications @SMHEC

ENEE 488A Topics In Cybersecurity @SMHEC

ENEE 440N Microprocessors @SMHEC

ENGL 393 Technical Writing @UMD

## **Senior Year, Spring Semester** (5 courses)

ENEE 408X Capstone Design, @UMD

ENEE 420N Communication Systems @SMHEC

ENEE 426N Communication Networks @SMHEC

ENEE 446N Digital Computer Design @SMHEC

ENEE 488B Direct Study: Navy Hardware @SMHEC

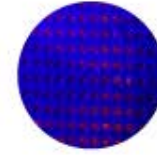


# ENEE 408R – Electric Bikes

Course Piloted Spring 2017, 15 Students, 3 teams

- Design Challenges
  - **URBAN BIKE** that can travel 50 miles in a single charge, can be fully charged in 2 hours
  - **MOUNTAIN BIKE** that can climb very steep hills (or climb a set of stairs)
  - **SELF DRIVING TRICYCLE** that can autonomously travel from one point of campus to another

# Student Teams



- Team Green (Urban) has 3EE and 3CpE
- Team Red (Mountain) has 4EE and 2CpE
- Team Yellow (Self Drive) has 1EE and 2CpE



# Urban Bike Design Issues

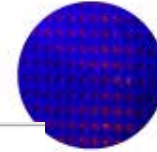


- Motor Selection (size, placement, efficiency)
- Power and energy
- Battery (characteristic, charging and discharging)
- Bicycle characteristics (weight, reliability)
- Metrics and Testing
- Add ons: wireless control, route and terrain mapping APP)

# Urban Bike – Finished Product

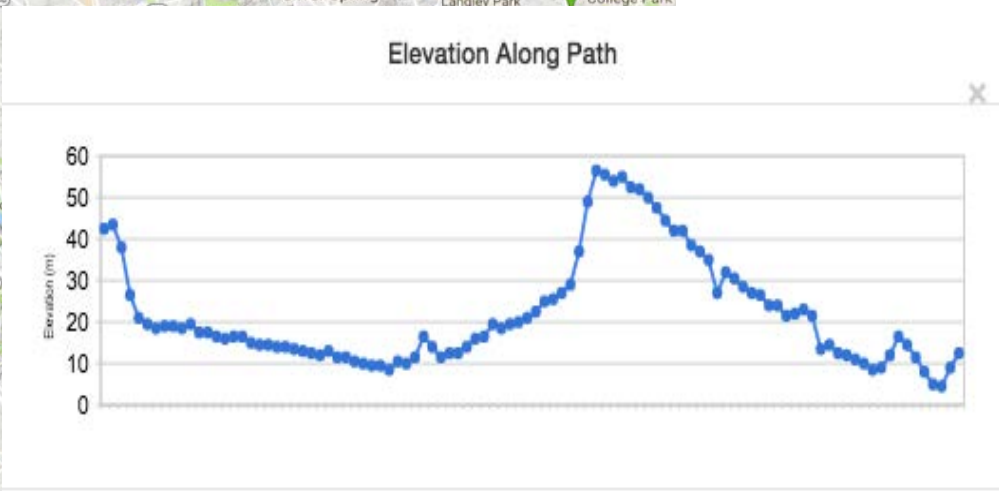


# Bike Router App



← → ↻ <https://bike-router.herokuapp.com/>

## My Bike Path Router 2.0



**Start:**

University of Maryland

**End:**

US Capitol, Washington, DC

Suggested routes:

- NE Branch Trail 10.5 mi. About 1 hour 0 mins Elevation Rating: 133.828
- Anacostia Tributary Trail System/NW Branch Trail 9.6 mi. About 54 mins Elevation Rating: 156.108
- NE Branch Trail 13.2 mi. About 1 hour 11 mins Elevation Rating: 88.835



Bicycling directions are in beta. Use caution – This route may contain streets that aren't suited for bicycling.

College Park, MD 20742, USA

9.6 mi. About 54 mins

1. Head west on Campus Dr toward Adelphi Rd 236 ft
- ↩ 2. Turn left onto Adelphi Rd 0.1 mi

Close



# Mountain Bike - Design Issues

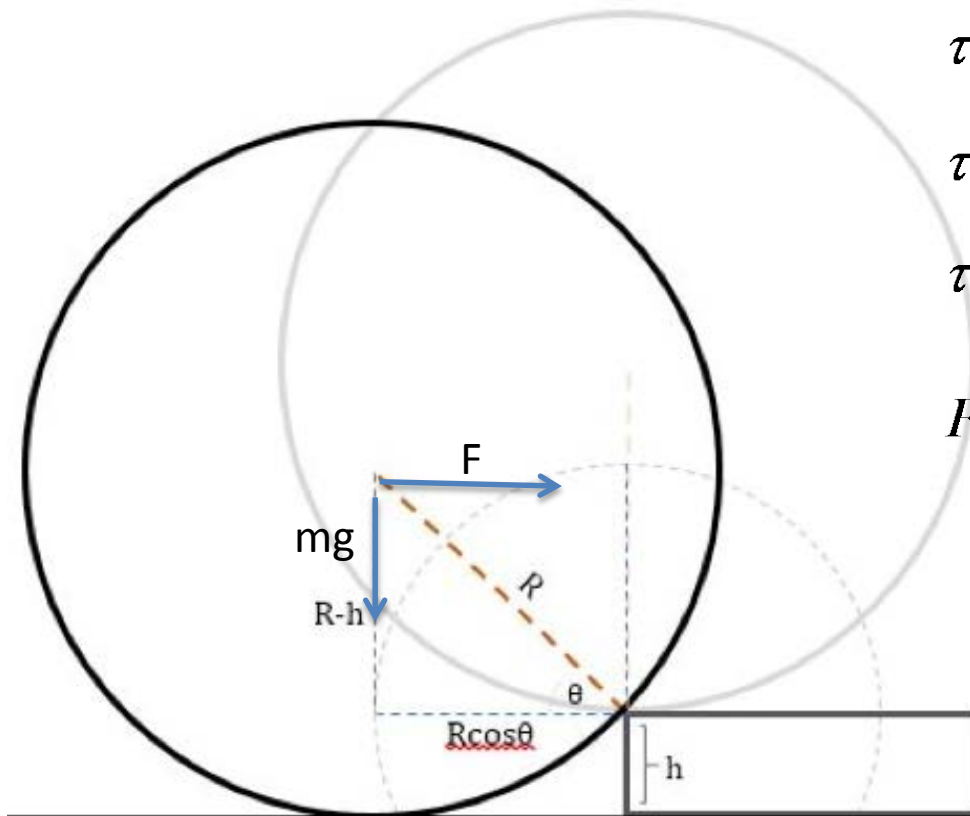
- Motor (torque, size, power, placement)
- Power and heating
- Power monitoring
- Battery charging
- Bicycle characteristics (weight, braking, suspension)
- Reliability Testing
- Add on: wireless control, anti-theft device, real-time system monitoring)



# Mountain Bike Finished Product



# Physics of Climbing Stairs



$$\tau_1 = F(R-h)$$

$$\tau_{mg} = mg(R \cos \theta) = mg(\sqrt{2hR - h^2})$$

$$\tau_1 = \tau_{mg} :$$

$$F = mg \frac{\sqrt{2hR - h^2}}{R - h}$$

*Given :*

$$m = 15\text{kg}(\text{bike}) + 75\text{kg}(\text{rider}) = 90\text{kg}$$

$$R = 0.35\text{m}, h = 0.18\text{m}, v = 1\text{m/s}$$

*Then :*

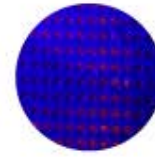
$$F = 1587\text{N}$$

$$\rightarrow P = Fv = 1587\text{W}$$

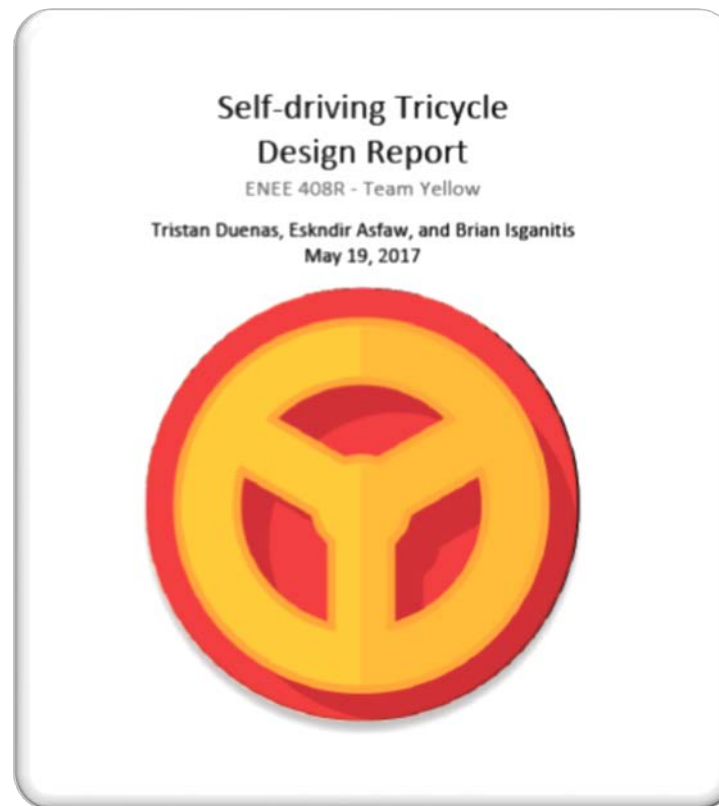
# Self Driving Tricycle Design Issues

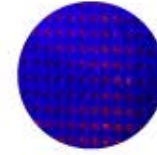
- Steering System – microprocessor controlled
- Braking System – microprocessor controlled
- Control– microprocessor controlled
- Obstacle recognition– sensors
- Wireless communication
- Path following and navigation– image processing

# Finished Product



# Ability to Write: Sample Final Report





Thank you!