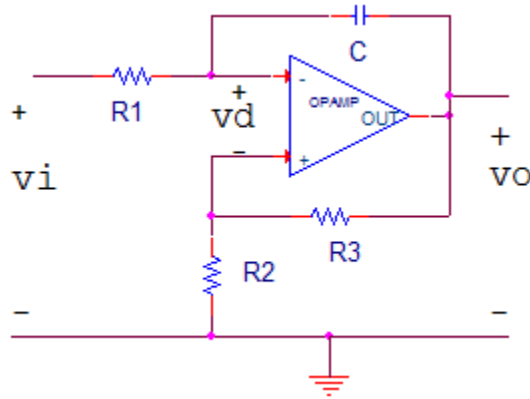


Circuits Fall 2017

#1. (6 points) For the following circuit assume that the op-amp is ideal (linear, zero input currents and zero input difference voltage= $v_d=0$).



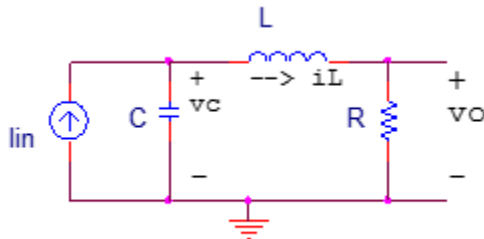
a) (3 points) Find the transfer function $v_o(s)/v_i(s)$ when $R_1=R_2=R_3=R$ and give its zeros and poles.

b) (3 points) Discuss stability of the circuit, including conditions and nature.

#2 (7 points) The following circuit is described by the equations

$$\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix} \frac{dx}{dt} = \begin{bmatrix} 0 & -1 \\ 1 & -R \end{bmatrix} x + \begin{bmatrix} 1 \\ 0 \end{bmatrix} i_{in}$$

$$v_o = [0 \quad R]x$$

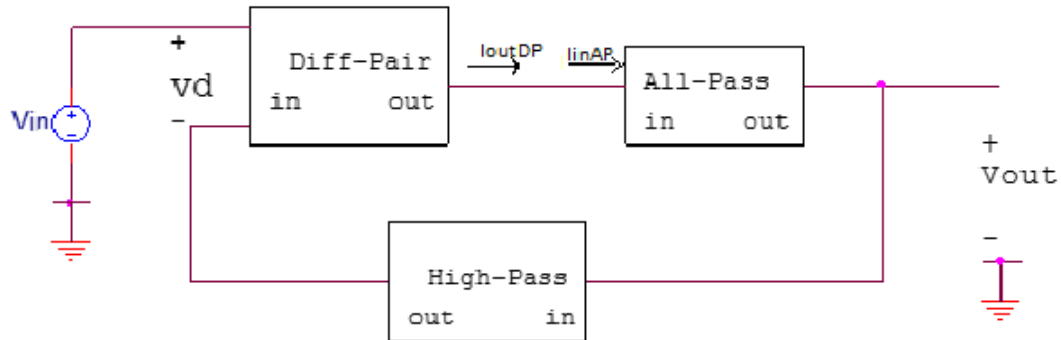


a) (2 points) Give x in terms of voltage and current variables labelled in the circuit.

b) (3 points) Give the transfer function $v_o/i_{in}(s)$.

c) (2 points) For C, L, R all positive, discuss if this is a low-pass, high-pass or band-pass circuit.

- #3) (7 points) The following is a sectioned circuit diagram for a feedback circuit consisting of a differential pair, an all-pass circuit, and a high-pass feedback circuit. The differential pair is described by $l_{outDP}/v_d = G_m$, the all-pass circuit is described by $v_{outAP}/l_{inAP}(s) = [s-a]/[s+a]$, and the high-pass feedback by $v_{outHP}/v_{inHP}(s) = Cs$; all of C , G_m , and a are positive.



- (3 points) Find the transfer function $V_{out}/V_{in}(s)$.
- (2 points) Show that there is a G_m for which this will be a sinusoidal oscillator; give the G_m and oscillation frequency, f_{osc} .
- (2 points) If the output of the high-pass section were to become shorted, discuss how that will affect a measurement of V_{out} in the laboratory.

Circuits Fall 2017 solutions

#1. a) $v_{R_2} = \frac{R_2}{R_2+R_3} v_o = \frac{1}{2} v_o$, $v_{R_1} = R_1 i = v_i - v_o - v_{R_2} = v_i - \frac{1}{2} v_o \Rightarrow i = \frac{1}{R} (v_i - \frac{1}{2} v_o)$
 $i_C = i = \alpha C v_x = \alpha C [v_o + v_{R_2} - v_o] = \alpha C [\frac{1}{2} v_o - v_o] = -\frac{1}{2} \alpha C v_o = \frac{1}{R} (v_i - \frac{1}{2} v_o)$
 $\Rightarrow -\frac{\alpha C}{2} v_o + \frac{1}{2} v_o = v_i \Rightarrow \frac{v_o}{v_i} = \frac{1}{(-\frac{\alpha C}{2} + \frac{1}{2})} = \frac{2}{-RC\alpha + 1} = \frac{-2/RC}{\alpha - 1/RC} = \frac{v_o}{v_i}$
 $\Rightarrow \text{a zero @ } \infty, \text{ a pole @ } \alpha_p = 1/RC$

b) If $R > 0, C > 0$ the circuit is unstable having a RHP pole giving impulse response $-\frac{2}{RC} e^{\pm/RC} 1(t)$

If $R=0$, the input is tied to (the limit when $R \rightarrow 0$) $\frac{1}{2} v_o \Rightarrow v_o = 2v_i \Rightarrow$ stable
 Similarly if $C=0$ as the input current is 0 giving $v_i = \frac{1}{2} v_o \Rightarrow$ stable

#2. summing currents at the top of C $\Rightarrow i_C = C \frac{dv_C}{dt} + i_L \Rightarrow C \frac{dv_C}{dt} = -i_L + i_{in}$
 \Rightarrow 1st eq $\Rightarrow x_1 = v_C$
 summing voltages around loop, C-L-R $\Rightarrow -v_C + L \frac{di_L}{dt} + R i_L = 0 \Rightarrow L \frac{di_L}{dt} = v_C - R i_L$
 \Rightarrow 2nd eq $\Rightarrow x_2 = i_L$

a) $\Rightarrow x = \begin{bmatrix} v_C \\ i_L \end{bmatrix}$

b) Taking Laplace transform $\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix} X(s) = \begin{bmatrix} 0 & -1 \\ 1 & -R \end{bmatrix} X(s) + \begin{bmatrix} 1 \\ 0 \end{bmatrix} I_{in}$, $V_o = [0 \ R] X(s)$
 $\Rightarrow X(s) = \left\{ \begin{bmatrix} \alpha C & 0 \\ 0 & \alpha L \end{bmatrix} - \begin{bmatrix} 0 & -1 \\ 1 & -R \end{bmatrix} \right\}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} I_{in} = \begin{bmatrix} \alpha C & 1 \\ -1 & \alpha L + R \end{bmatrix}^{-1} \begin{bmatrix} 1 \\ 0 \end{bmatrix} I_{in} = \frac{1}{\alpha^2 LC + \alpha RC + 1} \begin{bmatrix} \alpha L + R \\ +1 \end{bmatrix} I_{in}$
 $V_o = [0 \ R] \begin{bmatrix} \alpha L + R \\ +1 \end{bmatrix} \frac{1}{\alpha C^2 + RC + 1} I_{in} \Rightarrow \frac{V_o}{I_{in}} = \frac{R}{LC\alpha^2 + RC\alpha + 1}$

c) This is a low pass circuit if R, L, C all > 0 as $\frac{V_o}{I_{in}} \Big|_{\alpha=j\omega \rightarrow \infty} = 0$

#3. a) $i_{in, top} = -G_m [v_{in} - C a v_{out}] = i_{in, AP} = \left(\frac{\alpha+a}{\alpha-a} \right) v_{out} \Rightarrow G_m v_{in} = \left[G_m C a + \left(\frac{\alpha+a}{\alpha-a} \right) \right] v_{out}$
 $\Rightarrow \frac{v_{out}}{v_{in}} = \frac{G_m}{G_m C a + \left(\frac{\alpha+a}{\alpha-a} \right)} = \frac{G_m (\alpha-a)}{G_m C a^2 + (1 - G_m C a) \alpha + a}$

b) For $G_m C a = 1$ which is $G_m C = 1/a$, $\frac{v_{out}}{v_{in}} = \frac{G_m (\alpha-a)}{G_m C a^2 + a} = \frac{1}{C} \frac{(\alpha-a)}{\alpha^2 + \frac{a}{G_m C}} = \frac{1}{C} \frac{(\alpha-a)}{\alpha^2 + a^2}$
 $\Rightarrow G_m = 1/Ca \Rightarrow$ pole on $j\omega$ axis
 $@ \pm \sqrt{-a^2} = \pm ja$, $\omega_{oscillation} = a = 1/G_m C$, $f_{osc} = \frac{\omega_{osc}}{2\pi} = \frac{a}{2\pi}$

c) If high-pass output = short \Rightarrow no feedback $\Rightarrow v_o = v_{in}$ killing oscillations
 $\Rightarrow \left(\frac{v_{out}}{v_{in}} \right) \Big|_{C=0} = \frac{G_m (\alpha-a)}{\alpha+a} \Rightarrow$ measure only "damped" responses, no self oscillation