

Digital Logic Design

ENEE 244-010x

Lecture 17

Announcements

- Exam next time
- Exam info, review sheet, solutions are all up on course webpage/Canvas
- Will do a review towards the end of class.

Agenda

- Last time:
 - Programmable Logic Devices (5.7-5.10)
- This time:
 - New topic: Flip-flops
 - The Basic Bistable Element (6.1)
 - Latches (6.2)
 - Timing Considerations (6.3)

Sequential Networks

- The logic networks studied so far are combinational networks:
 - The outputs at any instant depend only upon the inputs present at that instant.
- Sequential Network:
 - The outputs at any instant are dependent not only upon the inputs present at that instant but also upon the past history of inputs.
- Sequential networks have memory.
 - The information preserved is referred to as the internal state, secondary state, or state of the network.

Sequential Networks

- Synchronous sequential network
 - Behavior is determined by the values of the signals at only discrete instants of time.
 - Master-clock generator which produces a sequence of clock pulses that sample the input.
- Asynchronous sequential network
 - Behavior of the network is immediately affected by the input signal changes.

Flip-Flop

- The basic logic element that provides memory in many sequential networks.
- Flip-flop itself is a simple sequential network.
 - All sequential networks require the existence of feedback.
 - Feedback is present in flip-flop circuits.
- Flip-flop has two stable conditions.
 - Each of this is associated with a state or storage of a binary symbol.

The Basic Bistable Element

- Central to all flip-flop circuits.
- Has two outputs Q, \bar{Q}

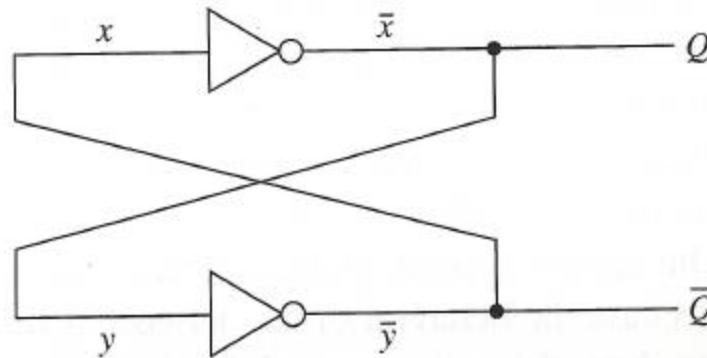


Figure 6.1 Basic bistable element.

- Two stable states:
 - $x = 0; \bar{x} = 1; Q = 1; y = 1; \bar{y} = 0; \bar{Q} = 0; x = 0;$
 - $\bar{Q} = x = \bar{y} = 0; Q = \bar{x} = y = 1$
 - $x = 1; \bar{x} = 0; Q = 0; y = 0; \bar{y} = 1; \bar{Q} = 1; x = 1;$
 - $\bar{Q} = x = \bar{y} = 1; Q = \bar{x} = y = 0$

The Basic Bistable Element

- When output line $Q = 1$ the element is storing a 1; when output line $Q = 0$ the element is storing a 0.

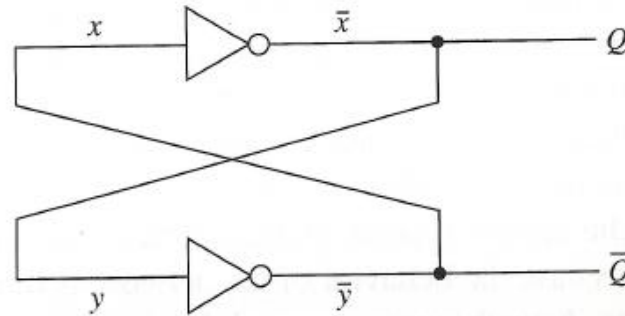


Figure 6.1 Basic bistable element.

- There is one more equilibrium condition that can exist. Occurs when the two output signals are halfway between logic-0 and logic-1.
- Known as metastable state.
 - Any small change causes the element to enter one of its two stable states.
 - Amount of time a device can stay in its metastable state is unpredictable.
 - Metastable state must be avoided.

The Basic Bistable Element

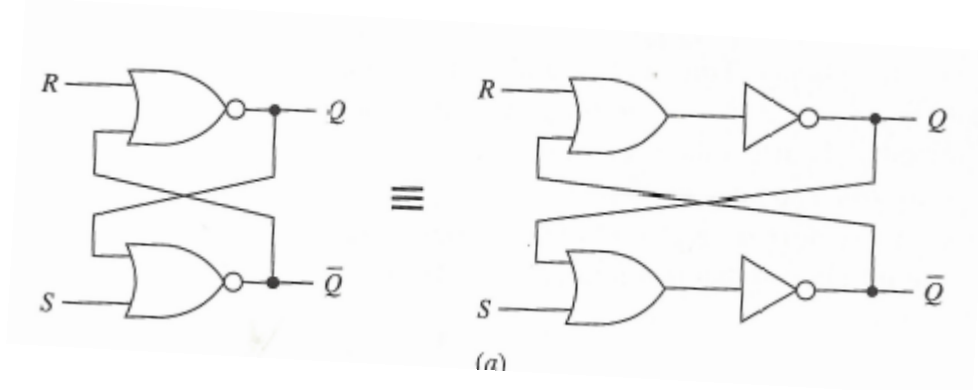
- Has no inputs.
- When power is applied, it becomes stable in one of its two stable states and remains in this state until power is removed.
- To be useful, must be able to force the device into a particular state.
- A flip-flop is a bistable device, with inputs, that remains in a given state as long as power is applied and until input signals are applied to cause its output to change.
- Inputs to flip-flops:
 - Asynchronous or direct input: a signal change produces an immediate change in the state of the flip-flop.
 - Synchronous input: A signal change does not immediately affect the state of the flip-flop. Affects it only when some control signal (clock) occurs.

Latches

- Latches are one class of flip-flops
- The timing of the output changes is not controlled
 - The output responds immediately to changes on the input lines.
 - Input lines are continuously being interrogated.
- Sections 6.4,6.5: flip-flops in which the timing of the output changes is controlled.

The SR (set-reset) Latch

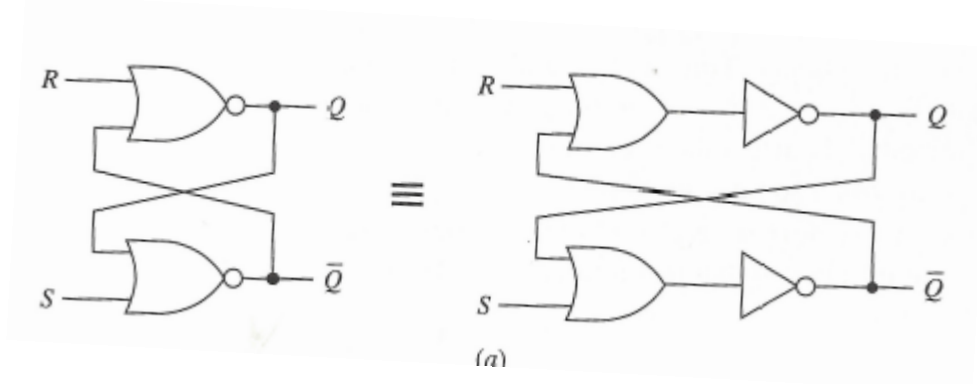
- Cross-coupling of two NOR gates.
- Two inputs: S, R referred to as the set and reset inputs
- Two outputs: Q, \bar{Q}



- $S = R = 0$ logic diagram simplifies to basic bistable element
- $R = 1; S = 0$ —latch is “reset”
- If R is returned to 0 then latch retains its present state
- $S = 1; R = 0$ —latch is “set”
- S,R are asynchronous inputs

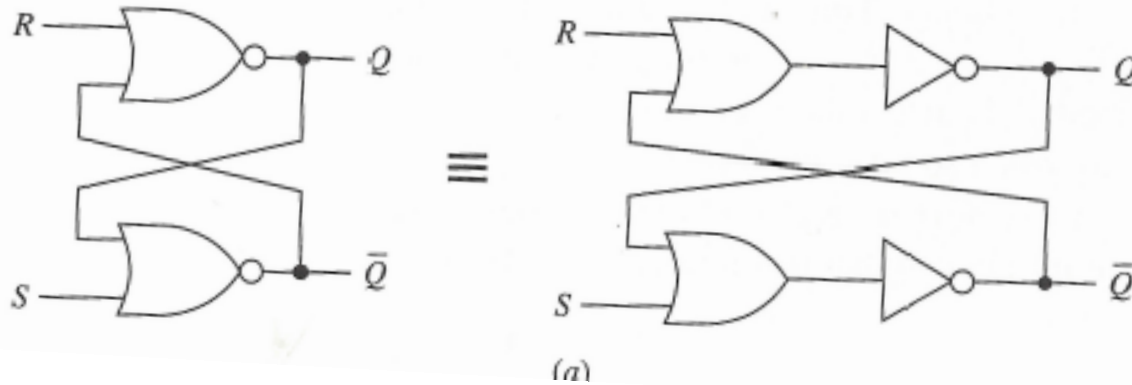
The SR (set-reset) Latch

- Cross-coupling of two NOR gates.
- Two inputs: S, R referred to as the set and reset inputs
- Two outputs: Q, \bar{Q}



- Consider the case where $S = R = 1$
 - Output of both NOR gates becomes 0, not complementary
- When inputs return to 0:
 - If one input returns to 0 before the other, the last input to stay at 1 determines the final state.
 - If both inputs return to 0 simultaneously, the device may enter its metastable state. Final state is unpredictable.
- $S = R = 1$ regarded as “forbidden state”

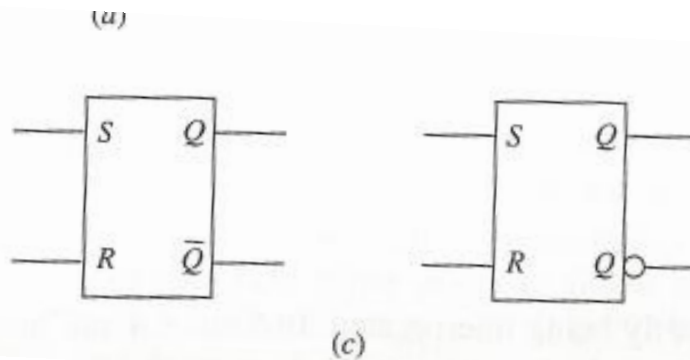
The SR Latch



Next state is the same as the previous state.

Inputs		Outputs	
S	R	Q^+	\bar{Q}^+
0	0	Q	\bar{Q}
0	1	0	1
1	0	1	0
1	1	0^*	0^*

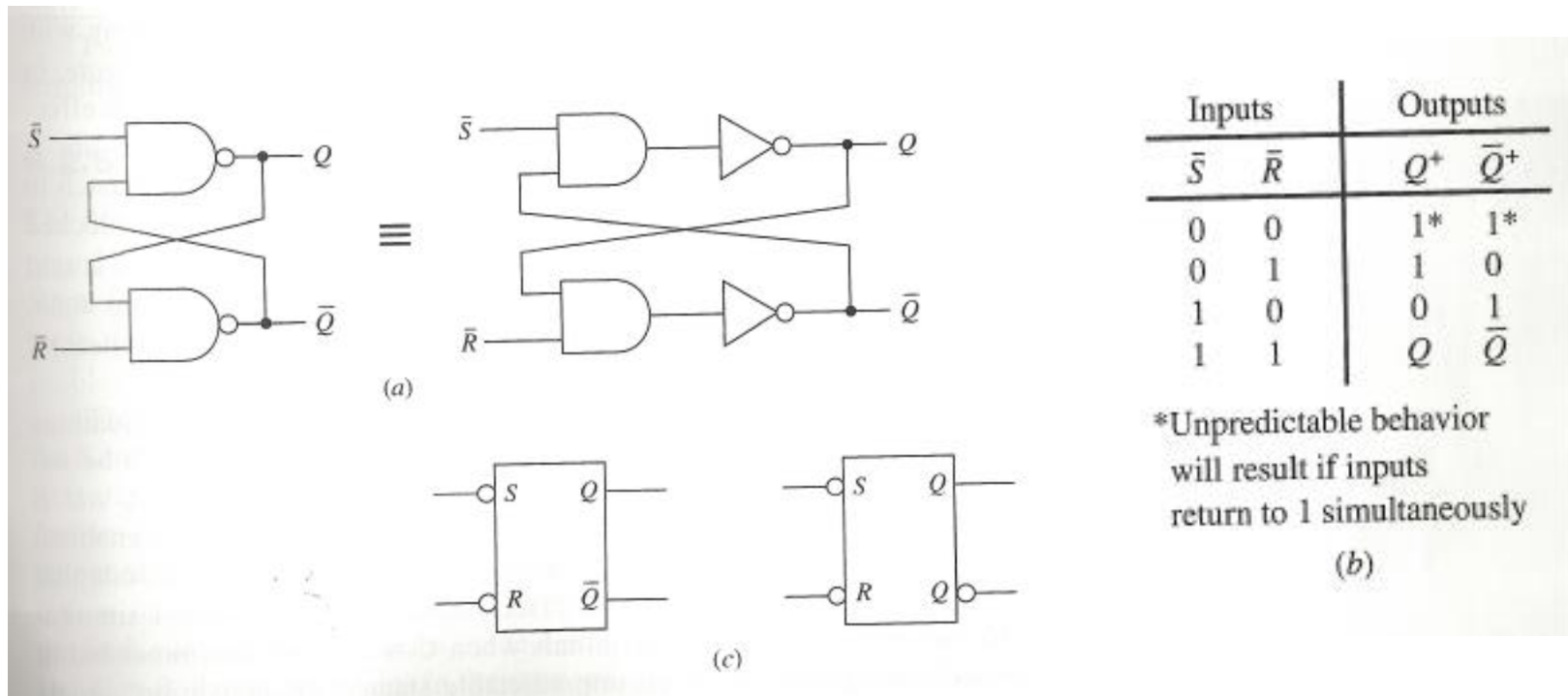
*Unpredictable behavior will result if inputs return to 0 simultaneously



Q^+, \bar{Q}^+ indicates the response of the latch at the Q, \bar{Q} output terminals as a consequence of applying the various inputs. Q^+ is called the next state of the latch.

The $\bar{S} \bar{R}$ Latch

- Cross-coupling of two nand-gates
- When $\bar{S} = \bar{R} = 1$ logic diagram reverts to the basic bistable element.
- Device has 2 stable states.

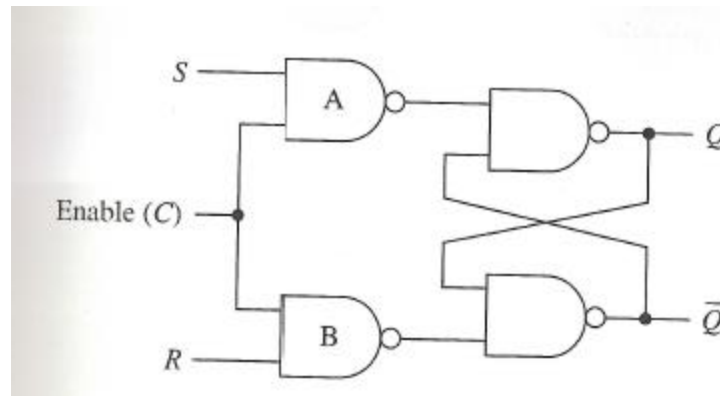


The Gated SR Latch

- Inputs for SR Latch and $\bar{S} \bar{R}$ Latch are asynchronous.
 - A change in the value of the inputs causes an immediate change of the outputs.
- Frequently desirable to prevent input activation signals from affecting the state of the latch immediately.
- “gated SR latch” or “SR latch with enable” is used.

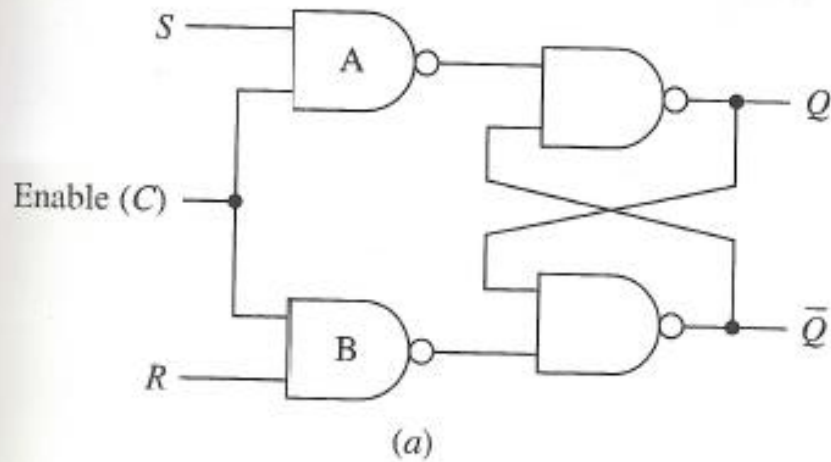
The Gated SR Latch

- $\overline{S} \overline{R}$ Latch along with 2 additional NAND gates and a control input C.
 - C is referred to as enable, gate or clock input.
- C determines when the S and R inputs become effective.



- As long as C input is 0, outputs of NAND gates are 1, keeps the $\overline{S} \overline{R}$ Latch in its current stable state.
 - Any changes to S,R are blocked.
 - Output is “latched” in its present state.
- When C is 1, the latch behaves as an SR Latch.
- If $S = R = C = 1$ then $Q = \overline{Q} = 1$.
 - If C then goes to 0, can enter metastable state.

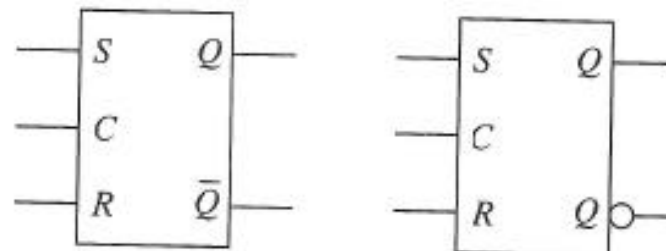
The Gated SR Latch



Inputs			Outputs	
S	R	C	Q^+	\bar{Q}^+
0	0	1	Q	\bar{Q}
0	1	1	0	1
1	0	1	1	0
1	1	1	1*	1*
X	X	0	Q	\bar{Q}

*Unpredictable behavior will result if S and R return to 0 simultaneously or C returns to 0 while S and R are 1

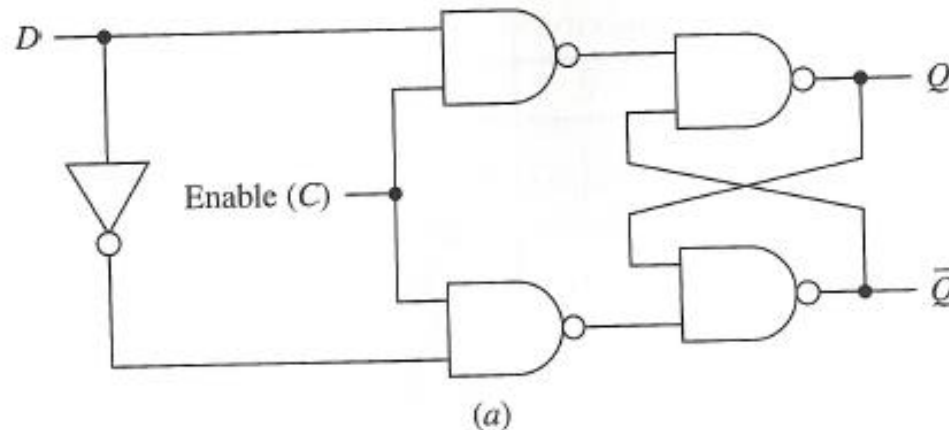
(b)



(c)

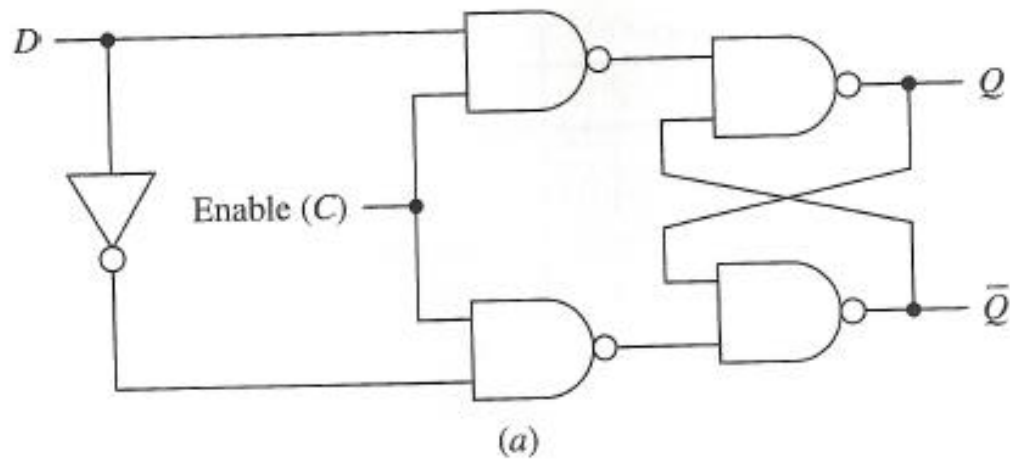
The Gated D Latch

- The latches discussed thus far each has an input combination that is not recommended.
- The gated D (data) latch does not have this problem.
- Gated SR-latch in which a not-gate is connected between the S and R terminals.



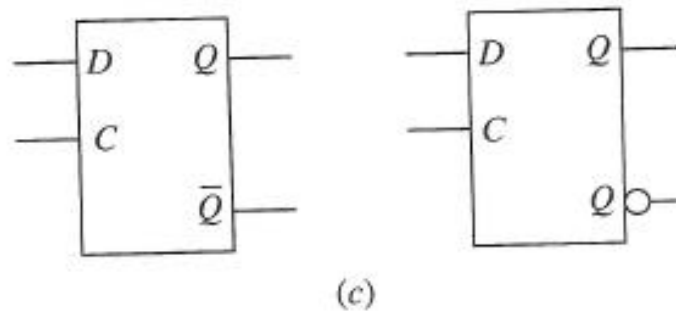
- Why does this help?

The Gated D Latch



Inputs		Outputs	
D	C	Q^+	\bar{Q}^+
0	1	0	1
1	1	1	0
X	0	Q	\bar{Q}

(b)



Timing Considerations

- Responses to inputs are not really immediate, but occur after some appropriate time delay.
- To achieve desired responses, certain timing constraints must be satisfied.

Propagation Delays

- The propagation delay is the time it takes a change in an input signal to produce a change in an output signal.
- Propagation delay from low to high: t_{pLH}
- Propagation delay from high to low: t_{pHL}

In general, these may be different.

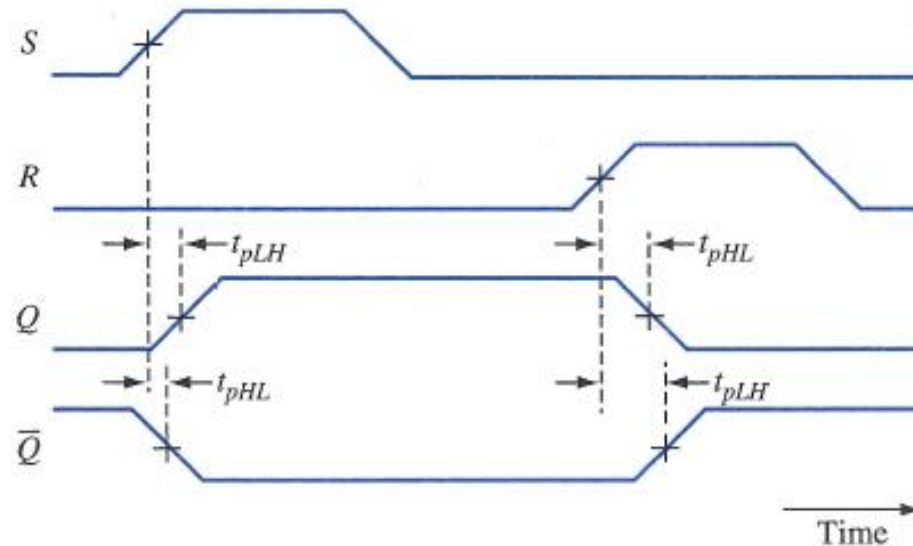


Figure 6.7 Propagation delays in an SR latch.

Timing Diagram

- Propagation delays from high-low, low-high assumed equal.
- When $S = R = 1$, both Q, \bar{Q} become 0.
- t_{15} , signals on S, R are simultaneously changed from 1 to 0.
 - Response of latch is unpredictable. Can be in 0-state, 1-state or metastable state.
 - Application of 1 on the set input terminal returns the latch to predictable.

